## User's Manual



# LIMIT L91 <br> Microprocessor Based Limit Controller 

UM - L91 September 2023

## Warning Symbol

This $\$ Symbol calls attention to an operating procedure, practice, or the like, which, if not correctly performed or adhered to, could result in personal injury or damage to or destruction of part or all of the product and system. Do NOT proceed beyond a warning symbol until the indicated conditions are fully understood and met.

## Use the Manual

\author{

- Installers <br> - System Designer <br> - Expert User <br> Read Chapter 1, 2 <br> Read All Chapters <br> Read Page 12
}


## NOTE: <br> It is strongly recommended that a process should incorporate a LIMIT like L91 which will shut down the equipment at a preset process condition in order to preclude possible damage to products or system.

Information in this user's manual is subject to change. without notice.
This manual is applicable for L91 units with software version 1.9 and later.

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## Chapter 1 Overview

## 1-1 General

The limit control L91 is a microprocessor based high or low limit safety device with a latching output. The relay contacts open if an abnormal condition during the process is higher than the high limit set point or lower than the low limit set point.

The unit is powered by 90-264 VAC or an optional 11-26
VACNDC power supply. It incorporates a 2 amp. form C relay for limit control, a universal input which is fully programmable for RTD PT100, thermocouple types J, K, T, E, B, R, S, N, L, 0~60mVolt, Volt* and Milliamps*. An optional second output is available for one of the following functions: alarm output, RS-485 communication, MA output, DC power supply output, limit annunciator output and event input. Alternative output options include; relay, SSR drive, Triac and Ma for retransmission. All mutually exclusive.
The input signal is digitized by using a 18-bit A to D converter. Its fast sampling rate ( 5 times/second) allows the L91 to respond quickly to input changes.

Digital communication RS-485 is available as an additional option. This option allows L91 to be integrated with supervisory control system. An alarm output is another option. A variety of alarm function and alarm modes can be programmed for a specific application. The DC power supply output option is used for an external sensor or transmitter. The event input option can be programmed for remote reset or remote lock signal input. The limit annunciator option can be used to energize an external audible alarm when limit is reached.
Ma retransmission option of Process variable or setpoint is also available.

Two kinds of method can be used to program L91. 1. use keys on front panel to program the unit manually, 2. Use a PC and setup software to program the unit via RS-485 port.

High accuracy, maximum flexibility, fast response and simple user friendly prompts are the main features of L91. NOTE: * Volt and Milliamp Inputs are NOT FM Approved.

## 1-2 Ordering Code

Power Input -
4: $90-264 \mathrm{VAC}, 50 / 60 \mathrm{HZ}$
5: 11-26 VAC or VDC
9: Special Order
Signal Inpuł
1: Standard Input
Thermocouple: J, K, T, E, B, R, S, N, L
RTD: PT100 DIN, PT100 JIS $\mathrm{mV}: 0 \sim 60 \mathrm{mV}$
2: Voltage: $0-1 \mathrm{~V}$ *
3: Voltage : 0-10 V *
4: Current: 0-20mA/4-20mA *
5: Voltage: 0-5, 1-5 V *

## Example

Standard Model:
L91-4110
90-264 VAC Operation

- Input: Standard Input
- Output 1: Relay
- Option: None


## Accessorles



0: None
1: Form A Relay $2 \mathrm{~A} / 240 \mathrm{VAC}$
2: SSR Drive 5VDC @ 30 ma
6: Triac Output, 1A / 240VAC, SSR
7: Isolated 20V / 25mA DC Supply
8: Isolated $12 \mathrm{~V} / 40 \mathrm{~mA}$ DC Supply
9: Isolated 5V / 80mA DC Supply
A: RS-485
B: Event input
C: SSR Drive 14VDC @ 40 ma
D: Retransmit 4/20, 0/20 Ma
E: Retransmit 1/5, 0/5 VDC
F: Retransmit 0/10 VDC
H: Special order

OM94-6 = Isolated 1A / 240VAC Triac Output Module ( SSR )
OM94-7 = 14VDC/40 ma SSR Drive module
DC 94-1 = Isolated 20V / 25mA DC Output Power Supply
DC 94-2 = Isolated 12V / 40mA DC Output Power Supply
DC 94-3 = Isolated 5V / 80mA DC Output Power Supply
CM 96-1 = Isolated RS-485 Interface Module
CM 96-3 $=$ Isolated 4/20, 0/20 MA Retransmission Output Module
CM 96-4 = Isolated 1/5, 0/5 VDC Retransmission Output Module
CM 96-5 = Isolated 0/10 VDC Retransmission Output Module
El96-1 = Event Input Module
NOTE: * Volt and Milliamp Inputs are NOT FM Approved.

## Related Products

P11A = Hand-held Programmer for L91,C91 Series Controller SNA1OA = Smart Network Adaptor for Third Party Software, Converts 255 channels of RS-485 or RS-422 to RS-232 Network
SNA1OB = Smart Network Adaptor for FD-Net Software, Converts 255 channels of RS-485 or RS-422 to RS-232 Network

## 1-3 Programming Port

## Programming Port



Open the housing Top view of L91

Figure 1-1 Programming Port Location
Note: The programming port is used for off-line setup and calibration procedures only. Do not attempt to make any connection to these jumpers when the unit is on-line. Port is for bench setup only.

## 1-4 Keys and Display

## KEYPAD OPERATION

SCROLL KEY $\square$
This key is used to:

1. Select a setpoint to be displayed.
2. Select a parameter to be viewed or adjusted.
3. Advance display from a parameter code to the next parameter code

ENTER KEY 4 seconds, 8 seconds
Press the scroll key for 4 seconds the display will enter the setup menu. Press this key for 8 seconds to enter the calibration mode.

## UP KEY $\quad$ -

This key is used to increase the selected parameter value during the lock indicator is off.

DOWN KEY $\quad$ V
This key is used to decrease the selected parameter value during the lock indicator is off.

RESET KEY REEEI
This key is used to:

1. Reset the limit condition after the process is within the limit.
2.Revert the display to the normal display.
3.Reset the latching alarm.
4.Reset the limit annunciator.

Note: If the RESET key is left pressed, only ONE reset operation will occur. If the unit subsequently goes into a state where reset is required again, the RESET key (or remote reset contacts) must be released (opened) and pressed (closed) again.

## UNLOCK KEY REEE 4 seconds

Press the RESET key for 4 seconds to enable up/down key function, and the lock indicator led will be extinguished.
However, this function is disabled when remote lock is selected for EIFN (Event input function). See section 3-16.


Figure 1-2 Front Panel Display

## INDICATORS

Opl: Output 1 status indicator
OP2: Output 2 status indicator
C: Degree C indicator
F: Degree F indicator
PV: Process value
HSP1 : High limit set point 1
LSP1: Low limit set point 1
SP2: Set point 2 for output 2
LOCK: Lock status indicator

## DISPLAY FORM

## Table 1-1 Display Form of Characters

| A | 8 | E | $E$ | 1 |  | N | $\square$ | S | 5 | X |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| B | $\square$ | F | $F$ | J | - | 0 | $\square$ | T | $t$ | Y | 3 |  |
| C | L | G | E | K | L | P | $P$ | U | 1 | Z |  |  |
| c | I | H | H | L | L | Q |  | V | $\underline{1}$ | ? | $\cdots$ |  |
| D | d | h | ¢ |  | - | R | r | W |  | = |  |  |

$\boldsymbol{\nabla}$ : These characters are displayed differently.

## How to display a 5-digit number :

For a number with decimal point the display will be shifted one digit right:
-199.99 will be displayed as -199.9, 4553.6 will be displayed as 4553
For a number without decimal point the display will be divided into two alternating phases:
-19999 will be displayed as:

45536 will be displayed as:

-9999 will be displayed as:


## NORMAL DISPLAY

During normal operation, the unit can be configured to display the process value, high limit or low limit set point (HSP1 or LSP1 dependent on OUT1 selection ) or the word SAFE.

## ABNORMAL DISPLAY

Whenever the process is outside the normal range, the process value will be displayed.

## SENSOR BREAK DISPLAY

If a break is detected in the sensor circuit, the display will show:

## 5En.b

## A-D FALLURE DISPLAY

If failure is detected in the A-D converter circuit, the display will show:

## RdEr

## POWER UP SEQUENCE



All segments of display and indicators are left off for 0.5 second.

All segments of display and indicators are lit for 1 second.

Display program code of the product for 1 second. The left diagram shows program no. 1 with version 21.

Display Date Code for 1 second. The left diagram shows Year 2001, Month February (2), Date $25^{\prime}$ th. This means that the product is produced on February 25'th, 2001. Note that the month code A is for October, $\mathbf{B}$ is for November and $\mathbf{C}$ is
|}|\Delta
|}|\Delta
FIJ futuredesicn


Display the serial number ( 001 ~999 ) for 1 second.

Display the hours used for 2 seconds. The left diagram shows that the unit has been used for 23456.7 hours since production.

Figure 1-3 Power Up Sequence

Setup Mode


| $\begin{aligned} & \text { Press } \begin{array}{l} \square \\ \text { for } 4 \mathrm{sec} \end{array} \\ & \hline \end{aligned}$ |  |  |
| :---: | :---: | :---: |
| $\begin{aligned} & 06 \\ & 00 \end{aligned}$ | INPT | Input type |
|  | UNIT | Process unit |
| $06$ | RESO | Display resolution |
|  | IN.LO | Low scale value for linear input |
| $\begin{aligned} & \square 6 \\ & 06 \end{aligned}$ | IN.HI | High scale value for linear |
| $\square$ | SHIF | PV shift (offset) value |
|  | FILT | PV filter time constant |
| $\square$ | OUT1 | Output 1 function |
| $\square$ | O1.HY | Output 1 hysteresis value |
|  | HSP.L | Lower limit of HSP1 |
| $\square$ | HSP.H | Upper limit of HSP1 |
| $\square$ | LSP.L | Lower limit of LSP1 |
| $\square$ | LSP.H | Upper limit of LSP1 |
| $\square$ | OUT2 | Output 2 function |
| $\square$ | ADDR | Address for digital |
| $\square$ | BAUD | Baud rate |
| $\square$ | PARI | Parity bit |
|  | AOFN | Analog output function |
|  | AOLO | Analog output low scale |
|  | AOHI | Analog output high scale |
|  | AL.FN | Alarm function |
|  | AL.MD | Alarm mode |
|  | AL.HY | Alarm hysteresis value |
|  | AL.FT | Alarm failure transfer |
|  | EIFN | Event input function |
|  | DISP | Normal display format |
|  | PV.HI | Max. historical PV |
|  | PV.LO | Min. historical PV |
|  | T.ABN | Abnormal time |
|  | $\square$ |  |

Note 1 .The flow charts show a complete listing of parameters. For the actual application the number of available parameters is dependent on the setup conditions, and should be less than that shown in the flow charts.

Note 2.Press key for 4 seconds to enable up/down key function, and the LOCK indicator led will be extinguished.

## 1-6 Limit Control Operation

## HIGH LIMIT OPERATION

If Hi . is selected for OUT1, the unit will perform high limit control. When power is applied the OUT1 relay is de-energized. After 6.5 seconds self-test period, if the process is below the high limit set point (HSP1), the output 1 relay will be energized and OP1 indicator will go off. If the process goes above the high limit set point, the relay will be de-energized, the OP1 indicator will go on and the display will show the process value. After the process falls below the high limit set point and the RESET key is pressed or the remote reset input is applied, the relay will be energized and the OP1 indicator will go off.
NOTE: Hysteresis is safe-sided.


Figure 1-4 High Limit Operation

## LOW LIMIT OPERATION

If Lo. is selected for OUT1, the unit will perform low limit control. When power is applied the OUT1 relay is de-energized. After 6.5 seconds self-test period, if the process is above the low limit set point (LSP1), the output 1 relay will be energized and OP1 indicator will go off. If the process goes below the low limit set point, the relay will be de-energized, the OP1 indicator will go on and the display will show the process value. After the process rises above the low limit set point and the RESET key is pressed or the remote reset input is applied, the relay will be energized and the OP1 indicator will go off. NOTE: Hysteresis is safe-sided.


Figure 1-5 Low Limit Operation

## HIGH/LOW LIMIT OPERATION

If Hi.Lo is selected for OUT1, the unit will perform high/low limit control. When power is applied the OUT1 relay is de-energized. After 6.5 seconds self-test period, if the process is below the high limit set point (HSP1) and above the low limit set point (LSP1), the output 1 relay will be energized and OP1 indicator will go off. If the process goes above the high limit set point or below the low limit set point, the relay will be de-energized, the OP1 indicator will go on and the display will show the process value. After the process is within the normal operation range, and the RESET key is pressed or the remote reset input is applied, the relay will be energized and the OP1 indicator will go off. NOTE: Hysteresis is safe-sided.


A, B, C, D, E, F = Reset is applied Ol.HY= Outputl hysteresis

Figure 1-6 High/Low Limit Operation

1－7 Parameter Descriptions

| Parameter Notation | Parameter Description | Range | Default Value |
| :---: | :---: | :---: | :---: |
| HSP1 | High Limit Set point 1 | Low：HSP．L High：HSP．H | $\begin{array}{\|l\|} \hline 100.0^{\circ} \mathrm{C} \\ \left(212.0^{\circ} \mathrm{F}\right) \end{array}$ |
| LSP1 | Low Limit Set point 1 | Low：LSP．L High：ISP． <br> High：LSP．H | $\begin{gathered} 0^{\circ} \mathrm{C} \\ \left(32.0^{\circ} \mathrm{F}\right) \end{gathered}$ |
| SP2 | Set point 2 Value for Output 2 | See Table 6－1 | $\begin{array}{\|c\|} \hline 90.0^{\circ} \mathrm{C} \\ \left(194.0^{\circ} \mathrm{F}\right) \\ \hline \end{array}$ |
| INPT | Input Type Selection | 0 J＿LE：J Jype thermocouple <br> 1 レーに［：K type thermocouple <br> 2 L＿LE：Ttype thermocouple <br> 3 E＿LE：Etype thermocouple <br> 4 ロ＿L「：B type thermocouple <br> 5 r＿t亡：R type thermocouple <br> 65 ＿L ：：stype thermocouple <br> 7 ח＿LE：Ntype thermocouple <br> 8 L＿LE：Ltype thermocouple <br> 9 PL．dா：PT100 ohms DIN curve <br> 10 PL．」S ：PT100 ohms JIS curve | $\begin{aligned} & 1 \\ & (0) \end{aligned}$ |


| Parameter Notation | Parameter Description | Range | Default Value |
| :---: | :---: | :---: | :---: |
| INPT | Input Type Selection | 114－コロ：4～20 <br> mA linear current＊ <br> 12日－コロ：0～20 <br> mA linear current＊ <br> 13 鸟－ <br> mV linear voltage <br> 14 亿－1上：0～1V <br> linear voltage＊ <br> 15 П－5ப：0～5V <br> linear voltage＊ <br> 16 1－5ப：1～5V <br> linear voltage＊ <br>  <br> linear voltage＊ | $\begin{aligned} & 1 \\ & (0) \end{aligned}$ |
| UNIT | Process Unit | 0 ar： <br>  Degree $C$ unit <br> 1 aF： <br>  Degree F unit <br> 2 $P_{L I}:$ <br>  Process unit | $\binom{0}{1}$ |
| RESO | Display Resolution |  | 1 |
| IN．LO | Low Scale Value for Linear Input | Low：－19999 <br> High：IN．HI | 0 |

NOTE：Inputs 11，12，14，15，16，and 17 are NOT FM Approved．

| Paramete Notation | Parameter Description | Range | Default Value |
| :---: | :---: | :---: | :---: |
| IN.HI | High Scale Value for Linear Input | Low: IN.LO High: 45536 | 100.0 |
| SHIF | PV Shift ( offset ) Value | $\begin{aligned} \text { Low: }-200.0^{\circ} \mathrm{C} \\ \left(-360.0^{\circ} \mathrm{F}\right) \\ \text { High: } 200.0^{\circ} \mathrm{C} \\ \left(300.0^{\circ} \mathrm{F}\right) \end{aligned}$ | 0.0 |
| FILT | PV Filter Time Constant |  | 2 |
| OUT1 | Output 1 Function |  | 2 |


| Parameter Notation | Parameter Description | Range | Default Value |
| :---: | :---: | :---: | :---: |
| O1.HY | Output 1 Hysteresis Value | $\begin{array}{\|l\|} \hline \text { Low: } 0.1 \\ \text { High: } 10.0 \mathrm{BC}(18.0 \mathrm{BF}) \\ \hline \end{array}$ | 0.1 |
| HSP.L | Lower Limit of HSP1 | Low: -19999 <br> High: HSP.H | $\begin{gathered} 0 \mathrm{C} \\ (32.0 \mathrm{~F}) \end{gathered}$ |
| HSP.H | Upper Limit of HSP1 | $\begin{array}{\|l\|l\|} \hline \text { Low: } & \text { HSP.L } \\ \text { High: } & 45536 \end{array}$ | $\begin{aligned} & 1000.0 \mathrm{C} \\ & (1832.0 \mathrm{~F}) \end{aligned}$ |
| LSP.L | Lower Limit of LSP1 | $\begin{aligned} & \text { Low: - } 19999 \\ & \text { High: LSP.H } \end{aligned}$ | $\begin{gathered} -100.0 \mathrm{C} \\ (-148.0 \mathrm{~F}) \end{gathered}$ |
| LSP.H | Upper Limit of LSP1 | $\begin{array}{\|l\|} \hline \text { Low: } \\ \text { High: } \\ \hline \end{array}$ | $\begin{gathered} 0 \mathrm{C} \\ (32.0 \mathrm{~F}) \end{gathered}$ |
| OUT 2 | Output 2 Function | 0 nanE: No function <br> 1 dโP5: DC power <br> 2 Lロйா̄: RS-485 <br> 3 BL $\overline{\mathrm{T}}$ : $\begin{gathered}\text { Communication } \\ \text { :Alarm output }\end{gathered}$ <br> 4 L_Bn: Limit <br> ${ }_{5} E_{1} F_{n}$ : Event input <br> 6 4-2 retransmission output <br>  refransmission output <br> 8 日 - IL: O-IV analog retrañsmission output <br>  <br> 10 $\boldsymbol{f}$ - $5 \underline{\Delta}: 1-5 \mathrm{~V}$ analog refransmission output <br> $11 \Omega$ - $10: 0-10 \mathrm{~V}$ analog retransmission output | - 4 |
| ADDR | Address Assignment of Digital COMM | Low: 1 <br> High: 255 | 1 |
| BAUD | Baud Rate of Digital COMM |  |  |


| Parameter Notation | Parameter Description | Range | Default Value |
| :---: | :---: | :---: | :---: |
| BAUD | Baud Rate of Digital COMM |  | 5 |
| PARI | Parity Bit of Digital COMM | $\begin{array}{ccl} 0 & \text { ローロー } & : 8 \text { bit } \\ \text { even parity } \end{array}$ | 0 |
| AOFN | Analog Output Function |  | 0 |
| AOLO | Analog Output Low Scale Value | Low：－19999 <br> High： 45536 | $\begin{gathered} O C \\ (32.0 \mathrm{~F}) \end{gathered}$ |
| AOH | Analog Output High Scale Value | $\begin{array}{lr} \text { Low: } & -19999 \\ \text { High: } & 45536 \end{array}$ | $\begin{gathered} 100.0 \mathrm{C} \\ (212.0 \mathrm{~F}) \end{gathered}$ |
| AL．FN | Alarm function | 6 PU．H．R ：Process value high alarm <br> 7 PUI． $\boldsymbol{7}$ ：Process value low alarm | 6 |


| Parameter Notation | Parameter Description | Range | Default Value |
| :---: | :---: | :---: | :---: |
| AL．MD | Alarm mode | 0 marī ：Normal alarm action <br> 1 Lヒとh ：Latching alarm action | 0 |
| AL．HY | Alarm hysteresis value | $\begin{aligned} \text { Low: } & 0.1 \\ \text { High: } & 10 \mathrm{BC} \\ & (18.0 \mathrm{BF}) \end{aligned}$ | 0.1 |
| AL．FT | Alarm failure transfer | 0 口FF：Alarm output goes off as unit fails <br> 1 an：Alarm output goes on as unit fails | 1 |
| EIFN | Event input function | 0 חanE ：No event function <br> 1 rESL ：Remote resef for output 1， output 1 on． <br> 2 Lロロレ゙：Remote lock for the unit | 0 |
| DISP | Normal display format | $0 \quad$ P上：Display process value <br> 15 （ ：Display HSP1 or LSP1 value <br> 2 5RFE：Display the word SAFE | 0 |
| PV．HI | Historical Max．value of PV | Low：－19999 <br> High： 45536 | Read Only |
| PV．LO | Historical Min．value of PV | Low：－19999 <br> High： 45536 | Read Only |
| T．ABN | Accumulated time during abnormal condition | Low： 0 <br> High：6553．5 minutes | Read Only |

## Chapter 2 Installation

.
Dangerous voltages capable of causing death are present in this instrument. Before installation or beginning any troubleshooting procedures the power to all equipment must be switched off and isolated. Units suspected of being faulty must disconnected and removed to a properly equipped workshop for testing and repair. Component replacement and internal must be made by a qualified maintenance person only.

!To minimize the possibility of fire or shock hazards, do not expose this instrument to rain or excessive moisture.

!Do not use this instrument in areas under hazardous conditions such as excessive shock, vibration, dirt, moisture, corrosive gases or oil. The ambient temperature of the areas should not exceed the maximum rating specified in Chapter 6.

## 2-1 Unpacking

Upon receipt of the shipment remove the unit from the carton and inspect the unit for shipping damage.
If any damage due to transit, report and claim with the carrier. Write down the model number, serial number, and date code for future reference when corresponding with our service center. The serial number ( $\mathrm{S} / \mathrm{N}$ ) and date code ( $\mathrm{D} / \mathrm{C}$ ) are labeled on the box and the housing of the unit.

## 2-2 Mounting

Make panel cutout to dimension shown in Figure 2-1.

Install both mounting clamps and insert the housing into panel cutout.


## Figure 2-1 Mounting Diagram

## 2-3 Wiring Precautions

* Before wiring, verify the label for correct model number and options. Switch off the power when checking.
* Care must be taken to ensure that maximum voltage rating specified on the label are not exceeded.
* It is recommended that power of these units to be protected by fuses or circuit breakers rated at the minimum value possible.
* All units should be installed inside a suitably grounded metal enclosure to prevent live parts being accessible from human hands and metal tools.
* All wiring must conform to appropriate standards of good practice and local codes and regulations. Wiring must be suitable for maximum voltage, current, and temperature rating of the system.
* Take care not to over-tighten the terminal screws.

Unused control terminals should not be used as jumper points as they may be internally connected, causing damage to the unit.

Verify that the ratings of the output devices and the inputs as specified in Chapter 6 are not exceeded.

* Electric power in industrial environments contains a certain amount of noise in the form of transient voltage and spikes. This electrical noise can enter and adversely affect the operation of microprocessor-based controls. For this reason we strongly recommend the use of shielded thermocouple extension wire which connects the sensor to the unit. This wire is a twisted-pair construction with foil wrap and drain wire. The drain wire is to be attached to earth ground at the sensor end only.


Figure 2-2 Lead Termination


Figure 2-3 Rear Terminal Connection Diagram

## 2-4 Power Wiring

The unit is supplied to operate at 11-26 VAC / VDC or 90-264VAC.Check that the installation voltage corresponds with the power rating indicated on the product label before connecting power to the unit.


!This equipment is designed for installation in an enclosure which provides adequate protection against electric shock. The enclosure must be connected to earth ground.

Local requirements regarding electrical installation should be rigidly observed. Consideration should be given to prevent from unauthorized person access to the power terminals.

## 2-5 Sensor Installation Guidelines

Proper sensor installation can eliminate many problems in a control system. The probe should be placed so that it can detect any temperature change with minimal thermal lag. In a process that requires fairly constant heat output, the probe should be placed closed to the heater. In a process where the heat demand is variable, the probe should be closed to the work area. Some experiments with probe location are often required to find this optimum position.

In a liquid process, addition of a stirrer will help to eliminate thermal lag. Since the thermocouple is basically a point measuring device, placing more than one thermocouple in parallel will provide an average temperature readout and produce better results in most air heated processes.

Proper sensor type is also a very important factor to obtain precise measurements. The sensor must have the correct temperature range to meet the process requirements. In special processes the sensor might need to have different requirements such as leakproof, anti-vibration, antiseptic, etc.

Standard thermocouple sensor limits of error are +/-4degrees F (+/- 2 degrees C ) or $0.75 \%$ of sensed temperature (half that for special ) plus drift caused by improper protection or an overtemperature occurrence. This error is far greater than controller error and cannot be corrected at the sensor except by proper selection and replacement.

## 2-6 Thermocouple Input Wring

Thermocouple input connections are shown in Figure 2-5. The correct type of thermocouple extension lead-wire or compensating cable must be used for the entire distance between the unit and the thermocouple, ensuring that the correct polarity is observed throughout. Joints in the cable should be

If the length of thermocouple plus the extension wire is too long, it may affect the temperature measurement. A 400 ohms K type or a 500 ohms J type thermocouple lead resistance will produce approximately 1 degree C temperature error .


Figure 2.5
Thermocouple Input Wiring

## 2-7 RTD Input Wiring

RTD connection are shown in Figure 2-6, with the compensating lead connected to terminal 4. For two-wire RTD inputs, terminals 4 and 5 should be linked. The three-wire RTD offers the capability of lead resistance compensation provided that the three leads are of same gauge and equal length.

Two-wire RTD should be avoided, if possible, for the purpose of accuracy. A 0.4 ohm lead resistance of a two-wire RTD will produce 1 degree C temperature error.


Figure 2-6
RTD Input Wiring

## 2-8 LInear DC Input Wiring

DC linear voltage and linear current connections are shown in Figure 2-7 and Figure 2-8 .


Figure 2.7
Linear Voltage Input Wiring *


Figure 2.8
Linear Current Input Wiring *

NOTE: Volt and Milliamp inputs are NOT FM Approved.

## 2-9 Event Input wiring



Open Collector
Input
Flgure 2-9
Event Input Wirlng

The event input can accept a switch signal as well as an open collector signal. The event input function (EIFN) is activated as the switch is closed or an open collector (or a logic signal) is pulled down.

## 2-10 Output 1 Wiring



## 2-11 Output 2 Wiring

Max. 2A

## Relay or Triac Output

|  |  |  |  |
| :---: | :---: | :---: | :---: |
| 2 2(3) |  |  |  |
|  |  |  | 8 |
| 4 (1)2] |  |  |  |
|  | 10 |  |  |



Figure 2-1 1 Output 2 Wiring

2-12 RS-485


## 2-13 Retransmission Output

Output options include: Ma and VDC


## Chapter 3 Programming

## 3-1 Process Input

Press $\Omega$ for 4 seconds to enter setup mode. Press $\square$ to select the parameter. The display will indicate the parameter symbol and the value ( or selection ) for that parameter.

INPT: Selects the sensor type and signal type for the process input.
UNIT: Selects the process unit.
RESO: Selects the location of the decimal point (Resolution) for most (not all) process related parameters.

IN.LO: Selects the low scale value for the Linear type input Hidden if: T/C or RTD type is selected for INPT

IN.HI: Selects the high scale value for the Linear type input Hidden if: T/C or RTD type is selected for INPT

## How to use IN.LO and IN.H:

If $4-20 \mathrm{~mA}$ is selected for INPT, let SL specifies the input signal Iow (ie. 4 mA ), SH specifies the signal high (ie. 20 mA ), S specifies the current input signal value, the conversion curve of the process value is shown as follows:
process value


Formula: $P \mathrm{PV}=\mathbb{N} . \mathrm{LO}+(\mathbb{N} . H \|-I N . L O) \frac{S-S L}{S H-S L}$
Example: a 4-20 mA current loop pressure transducer with range $0-15 \mathrm{~kg} / \mathrm{cm}^{2}$, is connected to input, then perform the following setup:
INPT $=4-20 \mathrm{~mA} \quad \operatorname{IN} . \mathrm{LO}=0.0$
UNIT $=$ PU $\quad \mathbb{N} . H=15.0$
RESO = 1-DP
Of course, you may select other value for RESO to alter the resolution.

## 3-2 Limit Control

Ol.HY: Output 1 hysteresis value. The hysteresis value is adjusted to a proper value to eliminate the relay jitter in a noisy environment.

## 3-3 Set Point Range

HSP.L : Lower limit of HSP1
Hidden if LO is selected for OUT1
HSP.H : Upper limit of HSP1
Hidden if LO is selected for OUT1
LSP.L : Lower limit of LSP1
Hidden if Hl is selected for OUT1
LSP.H : Upper limit of LSP1
Hidden if Hl is selected for OUT1
HSP.L and HSP.H in setup menu are used to confine the adjustment range of HSP1. LSP.L and LSP.H are used to confine the adjustment range of LSP1.

## 3-4 PV Shift

In certain application it is desirable to shift the indicated value from its actual value. This can be easily accomplished with this unit by using the PV shift function.

Cycle the unit to the SHIF parameter by using the scroll key. The number you adjust here, either positive or negative, will be added to the actual value. The SHIF function will alter PV

SHIF: PV shift (input correction) value

## 3-5 Digital Filter

In certain applications the process value is too unstable to be read. To Improve this a programmable low pass filter incorporated in the L91 can be used. This is a first order filter with time constant specified by FILT parameter which is contained in setup menu. The FLLT is defaulted to 0.5 sec . before shipping. Adjust FILT to change the time constant from 0 to 60 seconds. 0 second represents no filter is applied to the input signal. The filter is characterized by the following diagram.


Figure 3-2 Filter Characteristics

## 3-6 Process Alarms

The output 2 will perform process alarm function by selecting ALM for OUT2 and PV.H.A or PV.L.A for AL.FN. If PV.H.A is selected the alarm will perform process high alarm. If PV.L.A is selected the alarm will perform process low alarm. The process alarm sets an absolute trigger level. When the process exceeds that absolute trigger level an alarm occurs. The trigger level is determined by SP2 (Set point 2 value) and AL.HY (Alarm hysteresis value). The hysteresis value is introduced to avoid interference action of alarm in a noisy environment. Normally AL.HY can be set with a minimum value(0.1).

Trigger levels for process high alarm are SP2 and SP2 -AL.HY. Trigger level for process low alarm are SP2 +AL. HY and Sp2.

There are two types of alarm mode can be selected, these are: normal alarm and latching alarm.

## Normal Alarm: AL.MD = NORM

When a normal alarm is selected, the alarm output is deenergized in the non-alarm condition and energized in an alarm condition.

## Latching Alarm: AL.MD = LTCH

If a latching alarm is selected, once the alarm output is energized, it will remain unchanged even if the alarm condition has been cleared unless the power is shut off or the RESET key (or remote reset button) is pressed.

## Failure Transfer: AL.FT = OFF or ON

In case of Sensor Break or A-D Failure occurs, the alarm output will be on or off according to the selection of AL.FT.

## Examples:

SP2 $=200$
AL.MD $=$ NORM

$$
\begin{aligned}
& \text { AL.HY }=10.0 \\
& \text { AL.FN }=\text { PV.H.A }
\end{aligned}
$$

## Examples:

## Process proceeds

Flgure 3.3 Normal Process Alarm
-


SP2 $=200$
AL.HY $=10.0$
AL.MD $=$ LTCH
AL.FN $=$ PV.H.A

## Process proceeds




次



## 3-7 RS-485 Communicatlon

Using a PC for data communication is the most economic way. The signal is transmitted and received through the PC communication Port (generally RS-232). Since a standard PC can't support RS-485 port, a network adaptor (such as SNA1OA, SNA1OB) has to be used to convert RS-485 to RS-232 for a PC if RS-485 is required for the data communication. Many RS-485 units (up to 247 units) can be connected to one RS-232, that is a PC with 4 comm ports can communicate with 988 units.

Select COMM for OUT2 in setup menu, the output 2 will perform RS-485 interface with Modbus RTU Mode protocol.

## Setup

1. Select COMM for OUT2
2. Set an unequal address (ADDR) for those units which are connected to the same port.
3. Set the Baud Rate (BAUD) and Parity Bit (PARI) such that these values are accordant with PC setup conditions.

## 3-8 Display Mode

The DISP in the setup menu is used to select the display format for the normal condition. If PV is selected, the display will indicate the process value. If SP1 is selected, the display will indicate HSP 1 value for high limit control (OUT $1=\mathrm{HI}$ ) and high/low limit control (OUTl = HI.LO) or indicate LSP 1 value for low limit control(OUT1 = LO). IF SAFE is selected, the display will indicate the word SAFE for the normal condition.

However the display will indicate the process value if the process value goes beyond high limit or low limit. If an error condition occurs, the display will indicate the error symbol. The SAFE display will return when the process has returned to within SAFE values. Depressing reset key will reset output relay.

## 3-9 SIgnal Condlitloner DC Power Supply

Three types of isolated DC power supply are available to supply an external transmitter or sensor. These are 20 V rated at $25 \mathrm{~mA}, 12 \mathrm{~V}$ rated at 40 mA and 5 V rated at 80 mA . The DC voltage is delivered to the output 2 terminals by selecting DCPS for OUT2 in setup menu.


Set
OU2 $=d[P 5$
DC Power Supply

Figure 3-5
DC Power Supply Application

Three-line
Transmitter or sensor


Bridge Type


## Caution:

Don't use the DC power supply beyond its rating current to avoid damage.
Purchase a correct voltage to suit your external devices. See ordering code in section 1-2.

## 3-10 Remote Reset

If EIFN is selected for OUT2 and REST is selected for EIFN, terminals $1 \& 2$ will act as remote reset input. Pressing remote reset button will perform the same function as pressing the RESET key. Refer to section 1-4 for RESET key function.


Setup
OUT2 = EIFN
EIFN = REST

Figure 3-6 Remote Reset Application

## 3-11 Remote Lock

If EIFN is selected for OUT2 and LOCK is selected for EIFN, terminals $1 \& 2$ will act as remote lock input. Turning the remote lock switch on will keep all the parameter setting from been changed.


Setup
OUT2 = EIFN
EIFN = LOCK

Figure 3-7 Remote Lock Application

## 3-12 LImlt Annunclator

If L_AN (Limit annunciator) is selected for OUT2, the output 2 will act as a Limit Annunciator. If the limit is or has been reached and the RESET key (or remote reset contacts)has not been pressed since the limit was reached, then the limit annunciator output will be energized and the OP2 indicator will be lit and remain unchanged until the RESET key or remote reset input is applied.

## 3-13 Reference Data

There are three reference data contained in setup menu. The reference data are read only data. The maximum historical PV, displayed by $!-H_{1}$, which shows the maximum process value since the last UNLOCK operation. The minimum historical PV, displayed by $P \underline{L}$ a , which shows the minimum process value since the last UNLOCK operation. The abnormal time, displayed by $\boldsymbol{L}$. R! $\square$, which shows the total accumulated time (minutes) during the process has been in abnormal condition since the last UNLOCK operation.

The values of reference data will be initiated as soon as the RESET key is pressed for 4 seconds (UNLOCK operation). After UNLOCK operation, the PV.HI and PV.LO values will start from the current process value and T.ABN value will start from zero.

## Chapter 4 Application



Figure 4-1 Over Temperature Protection with Remote Reset

## Chapter 5 Callbration

Do not proceed through this section unless there is a definite need to re-calibrate the controller. Otherwise, all previous calibration data will be lost. Do not attempt re-calibration unless you have appropriate calibration equipment. If calibration data is lost, you will need to return the unit to your supplier who may change you a service fee to re-calibrate the unit.

Entering calibration mode will break the control loop. Make sure that if the system is allowable to apply calibration mode.

Equipment needed for calibration:
(1) A high accuracy calibrator (Fluke 5520A Calibrator recommended) with following function:
$0-100 \mathrm{~mA}$ millivolt source with $+/-0.005 \%$ accuracy
$0-10 \mathrm{~V}$ voltage source with $+/-0.005 \%$ accuracy 0-20mA current source with $+/-0.005 \%$ accuracy 0-300 ohm resistant source with $+/-0.005 \%$ accuracy
(2) A test chamber providing $25^{\circ} \mathrm{C}-50^{\circ} \mathrm{C}$ temperature range
(3) A switching network (SCANNER 80, optional for automatic calibration)
(4) A calibration fixture equipped with programming units (optional for automatic calibration)
(5) A PC with calibration software FD-Net and Smart Network Adaptor SNA1OB (optional for automatic calibration)

Since each unit needs 30 minutes to warm up before calibration.

The calibration procedures described in the following are a step by step manual procedures.

Apply Enter Key (press for 8 seconds) to enter the calibration mode. see Figure 5-1.


Step 1: Calibrate Zero of A to D converter.
Short terminal 4 and 5 , then press $\Omega$ for at least 4 seconds. The display will blink a moment. If the display didn't blink, then the calibration has failed.

Step 2: Calibrate Gain of A to D converter.
Send a span signal to terminal 4 and 5 with correct polarity.
The span signal is 60 mV for thermocouple input, 1 V for $0-1 \mathrm{~V}$ input, 10 V for $0-10 \mathrm{~V}$ input and 20 mA for $0-20 \mathrm{~mA}$ input.
Press $\square$ for at least 4 seconds. The display will blink a moment. If the display didn't blink, then the calibration failed.

Step 3: Calibrate offset of cold junction.
Setup the equipment according to the following diagram for calibrating the cold junction compensation. Note that a K type thermocouple must be used.

Figure 5-2
Cold Junction


Stay at least 20 minutes in stillair room room temperature $25+/-3 C$

## NOTE: The unit under calibration is powered in a still-air room at a temperature $25+/-3$ C. Allow at least 20 minutes for warming up.

The L91 being calibrated for Cold Junction Compensation MUST be programmed for $\mathrm{Kt} / \mathrm{c}$ input, Celsius display prior to performing the CJTL calibration.

Set the calibrator to be configured as K type thermocouple output. Calibrator must have an internal compensation. Send a 0.00 C signal to the unit under calibration.

With CJTL on the display adjust the value to 0.00 reading. Once adjusted, Press $\square$ for at least 4 seconds. The display will blink a moment. If the display didn't blink, then the calibration failed.

Step 4: Calibrate gain of cold junction.
Setup the equipment same as step 3.

## NOTE: The unit under calibration must powered at an ambient temperature of $50 \mathrm{C}+/-3$. Allow at least 20 minutes for warming up.

The L91 being calibrated for Cold Junction Compensation MUST be programmed for $\mathrm{K} \mathrm{t} / \mathrm{c}$ input, Celsius display prior to performing the CJG calibration.

Set the calibrator to be configured as K type thermocouple output. Calibrator must have an internal compensation. Send a 0.00 C signal to the unit under calibration.

With CJG on the display adjust the value to 0.00 reading. Once adjusted, Press $\Omega$ for at least 4 seconds. The display will blink a moment. If the display didn't blink, then the calibration failed.

Step 5: Calibrate RTD reference voltage.
Send a 100 ohms signal to terminal 3,4 and 5 according to
Figure 5-3.


Figure 5-3 RTD Calibration

Press for at least 4 seconds. The display will blink a moment. If the display didn't blink, then the calibration failed.

Step 6: Calibrate RTD serial resistance.
Change the ohm's value of the calibrator to 300 ohms. Press Q for at least 4 seconds. The display will blink a moment. If the display didn't blink, then the calibration failed.

## Chapter 6 Specifications

## Power

90-264 VAC, 49-63 Hz, $10 \mathrm{VA}, 5 \mathrm{~W}$ maximum
11-26 VACNDC, 10 VA, 5 W maximum
Input
Resolution: 18 bits
Sampling: 5 times/second
Maximum Rating: -2 VDC minimum, 12 VDC maximum
(1 minute for mA input)
Temperature Effect: A1.5 uV / ${ }^{\circ} \mathrm{C}$
Sensor Lead Resistance Effect:
T/C: 0.2 uV/ohm
3-wire RTD: $2.6^{\circ} \mathrm{C} / 0 h m$ of resistance difference of two leads
2-wire RTD: $2.6^{\circ} \mathrm{C} /$ ohm of resistance sum of two leads
Burn-out Current: 200nA
Common Mode Rejection Ratio (CMRR): 120db

## Sensor Break Detection:

Sensor open for TC, RTD and mV inputs, below 1 mA for 4-20 mA input, below 0.25 V for $1-5 \mathrm{~V}$ input, unavailable for other inputs.

## Sensor Break Responding Time:

Within 4 seconds for TC, RTD and mA inputs,
0.1 second for 4-20 mA and 1-5V inputs.

## Data Communication

Interface : RS-485 ( up to 247 units )
Protocol : Modbus Protocol RTU mode
Address : 1-247
Baud Rate : $0.3 \sim 38.4$ Kbits/sec
Data Bits : 8 bits
Parity Bit : None, Even or Odd
Stop Bit : 1 or 2 bits
Communication Buffer : 50 bytes

## Characterlstlcs:

| Type | Range | Accuracy <br> $@ 25^{\circ} \mathrm{C}$ | Input <br> Inpedance |
| :---: | :---: | :---: | :---: |
| J | $-120^{\circ} \mathrm{C}-1000^{\circ} \mathrm{C}$ <br> $\left(-184^{\circ} \mathrm{F}-1832^{\circ} \mathrm{F}\right)$ | $+/-2 \mathrm{C}$ | $2.2 \mathrm{M} \Omega$ |
| K | $-200^{\circ} \mathrm{C}-1370^{\circ} \mathrm{C}$ <br> $\left(-328^{\circ} \mathrm{F}-2498^{\circ} \mathrm{F}\right)$ | $+/-2 \mathrm{C}$ | $2.2 \mathrm{M} \Omega$ |
| T | $-250^{\circ} \mathrm{C}-400^{\circ} \mathrm{C}$ <br> $\left(-418^{\circ} \mathrm{F}-752^{\circ} \mathrm{F}\right)$ | $+/-2 \mathrm{C}$ | $2.2 \mathrm{M} \Omega$ |
| E | $-100^{\circ} \mathrm{C}-900^{\circ} \mathrm{C}$ <br> $\left(-148^{\circ} \mathrm{F}-1652^{\circ} \mathrm{F}\right)$ | $+/-2 \mathrm{C}$ | $2.2 \mathrm{M} \Omega$ |
| B | $0^{\circ} \mathrm{C}-1820^{\circ} \mathrm{C}$ <br> $\left(-32^{\circ} \mathrm{F}-3308^{\circ} \mathrm{F}\right)$ | $+/-2 \mathrm{C}$ <br> $\left(200^{\circ} \mathrm{C}-\right.$ <br> $\left.1820^{\circ} \mathrm{C}\right)$ | $2.2 \mathrm{M} \Omega$ |
| R | $0^{\circ} \mathrm{C}-1767.8^{\circ} \mathrm{C}$ <br> $\left(-32^{\circ} \mathrm{F}-3214^{\circ} \mathrm{F}\right)$ | $+/-2 \mathrm{C}$ | $2.2 \mathrm{M} \Omega$ |
| S | $0^{\circ} \mathrm{C}-1767.8^{\circ} \mathrm{C}$ <br> $\left(-32^{\circ} \mathrm{F}-3214^{\circ} \mathrm{F}\right)$ | $+/-2 \mathrm{C}$ | $2.2 \mathrm{M} \Omega$ |
| N | $-250^{\circ} \mathrm{C}-1300^{\circ} \mathrm{C}$ <br> $\left(-418^{\circ} \mathrm{F}-2372^{\circ} \mathrm{F}\right)$ | $+/-2 \mathrm{C}$ | $2.2 \mathrm{M} \Omega$ |
| L | $-200^{\circ} \mathrm{C}-900^{\circ} \mathrm{C}$ <br> $\left(-328^{\circ} \mathrm{F}-1652^{\circ} \mathrm{F}\right)$ | $+/-2 \mathrm{C}$ | $2.2 \mathrm{M} \Omega$ |
| PT100 <br> $(\mathrm{DIN})$ | $-210^{\circ} \mathrm{C}-700^{\circ} \mathrm{C}$ <br> $\left(-346^{\circ} \mathrm{F}-1292^{\circ} \mathrm{F}\right)$ | $+/-0.4 \mathrm{C}$ | $1.3 \mathrm{~K} \Omega$ |
| PT100 <br> $(\mathrm{JIS})$ | $-200^{\circ} \mathrm{C}-600^{\circ} \mathrm{C}$ <br> $\left(-328^{\circ} \mathrm{F}-1112^{\circ} \mathrm{F}\right)$ | $+/-0.4 \mathrm{C}$ | $1.3 \mathrm{~K} \Omega$ |
| mV | $-8 \mathrm{mV}-70 \mathrm{mV}$ | $+/-0.05 \%$ | $2.2 \mathrm{M} \Omega$ |
| mA | $-3 \mathrm{~mA}-27 \mathrm{~mA}$ | $+/-0.05 \%$ | $100 \Omega$ |
| V | $-1.3 \mathrm{~V}-11.5 \mathrm{~V}$ | $+/-0.05 \%$ | $510 \mathrm{~K} \Omega$ |

Table 6-1 Input Characteristics

## Event Input

Logic Low: -10V minimum, 0.8 V maximum.
Logic High: 2V minimum, 10 V maximum.
Functions: Remote reset, remote lockout.

## Output 1 / Output 2

Relay Rating: 2A/240 VAC, life cycles 200,000 for resistive load.
Pulsed Voltage: Source Voltage 5V, current limiting resistance 66 ohms.

Triac (SSR) Output
Rating: 1/240 VAC
Inrush Current: 20A for 1 cycle
Min. Load Current: 50 mA rms
Max. Off-state Leakage: 3 mA rms
Max. On-state Voltage: 1.5 V rms Insulation Resistance: 1000 Mohms min. at 500 VDC
Dielectric Strength: 2500 VAC for 1 minute
DC Voltage Supply Characteristics ( Installed at Output 2 )

| Type | Tolerance | Max. Output <br> Current | Ripple <br> Voltage | Isolation <br> Barrier |
| :---: | :---: | :---: | :---: | :--- |
| 20 V | $+/-0.5 \mathrm{~V}$ | 25 mA | $0.2 \mathrm{Vp}-\mathrm{p}$ | 500 VAC |
| 12 V | $+/-0.3 \mathrm{~V}$ | 40 mA | $0.1 \mathrm{Vp}-\mathrm{p}$ | 500 VAC |
| 5 V | $+/-0.15 \mathrm{~V}$ | 80 mA | $0.05 \mathrm{Vp}-\mathrm{p}$ | 500 VAC |

## Analog Retransmission

Functions: Process Variable
Output Signal: 4-20 mA, 0-20 mA, 0-5V, 1-5V, 0-10V
Resolution : 15 bits
Accuracy : +/-0.05 \% of span +/-0.0025 \%/ C
Load Resistance : 0-500 ohms ( for current output)
10 K ohms minimum ( for voltage output )
Regulation: 0.01 \% for full load change
Settling Time: 0.1 sec . (stable to 99.9 \% )
Breakdown Volts: 1000 VAC min.
Linearity Error : +/-0.005 \% of span
Temp Effect: +/-0.0025 \% of span / C
Saturation Low : 0 mA ( or OV )
Saturation High : 22.2 mA ( or $5.55 \mathrm{~V}, 11.1 \mathrm{~V}$ min. )
Output Range : $0-22.2 \mathrm{~mA}(0-20 \mathrm{~mA}$ or $4-20 \mathrm{~mA})$

$$
\begin{aligned}
& 0-5.55 V(0-5 V, 1-5 V) \\
& 0-11.1 \vee(0-10 V)
\end{aligned}
$$

## User Interface

4-digit LED Displays: 0.4" (10mm),
keypad: 4 keys
Programming Port: For automatic setup, calibration and testing.
Communication Port: Connection to PC for supervisory control.
Limit Control: High Limit, Low limit and High/Low Limit programmable

## Digital Filter

Function: First order
Time Constant: $0,0.2,0.5,1,2,5,10,20,30,60$ seconds programmable

## Environmental \& Physical

Operating Temperature : $-10^{\circ} \mathrm{C}$ to $50^{\circ} \mathrm{C}$
Storage Temperature : $-40^{\circ} \mathrm{C}$ to $60^{\circ} \mathrm{C}$
Humidity : 0 to $90 \%$ RH ( non-condensing )
Insulation Resistance : 20 Mohms min. ( at 500 VDC )
Dielectric Strength : 2000 VAC, $50 / 60 \mathrm{~Hz}$ for 1 minute
Vibration Resistance : $10-55 \mathrm{~Hz}, 10 \mathrm{~m} / \mathrm{s}$ for 2 hours
Shock Resistance : $200 \mathrm{~m} / \mathrm{s}^{2}(20 \mathrm{~g}$ )
Moldings : Flame retardant polycarbonate
Dimensions: $48 \mathrm{~mm}(\mathrm{~W}) \times 48 \mathrm{~mm}(\mathrm{H}) \times 94 \mathrm{~mm}(\mathrm{D})$,
86 mm depth behind panel
Weight : 150 grams

## Approval Standards

Safety : UL/cUR: QUYX2-QUYX8
FM, CE Approved

Protective Class :
IP30 front panel, indoor use,
IP 20 housing and terminals ( with protective cover)
EMC EN61326

## Warranty and Return Statement:

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The most recent list of chemicals known to the State of California can be seen at:
https://oehha.ca.gov/media/downloads/proposition-65//p65list102618.pdf
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